IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

Patentee:

Mark D. Levedahl

U.S. Patent No.:

US 7,092,924 B1

Issue Date:

August 15, 2006

Serial No.:

10/086,988

Filing Date:

February 28, 2002

Confirmation No.:

6322

Title:

Method and System for Assigning Observations

Commissioner for Patents P.O. Box 1450 Alexandria, VA 22313-1450

Dear Sir:

REQUEST FOR CERTIFICATE OF CORRECTION UNDER 37 CFR § 1.322

It is respectfully requested that a Certificate of Correction be issued in accordance with the enclosed Form PTO-1050. The error involved is believed to be a Patent Office error, and it is believed that no fee is due in association with this request for a Certificate of Correction. However, the Commissioner is hereby authorized to charge any fees or credit any overpayments to Deposit Account No. 02-0384 of Baker Botts L.L.P.

It is respectfully submitted that a significant error is present in the printed patent, that correction thereof in accordance with the enclosed Form PTO-1050 is required in order that no misunderstanding will occur.

Respectfully submitted, BAKER BOTTS L.L.P. Attorneys/for Applicant

Bradley P. Williams Rev. No. 40,227

Date: $\frac{5/29/09}{}$

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UNITED STATES PATENT AND TRADEMARK OFFICE CERTIFICATE OF CORRECTION

Patent No.: US 7,092,924 B1 Dated: August 15, 2006 Inventor(s): Mark D. Levedahl

It is certified that errors appear in the above-identified patent and that said Letters Patent is hereby corrected as shown below:

Column 5:

Lie 38, after "of these subject to:" delete " $m \le n \le N$ " and insert - - $m \le n \le N$ - -.

Column 6:

Line 19, delete Equation (5) and insert - -

$$\forall (i \neq j \ and \ a(j) > 0)$$

Line 27, delete Equation (6) and insert - -

$$P_{a} = \frac{e^{-\bar{x}^{T}R^{-1}\bar{x}/2}}{(2\pi)^{M/2}\sqrt{|R|}} \prod_{i}^{m} \frac{e^{-\left[A_{i} - B_{\sigma(i)} - \bar{x}\right]^{r}\left(P_{i} + Q_{\sigma(i)}\right)^{-1}\left[A_{i} - B_{\sigma(i)} - \bar{x}\right]/2}}{(2\pi)^{M/2}\sqrt{|P_{i} + Q_{\sigma(i)}|}}$$

Column 8:

Line 19, delete Equation (11) and insert

$$g = 2 \ln \left[\frac{\beta_{t} P_{TA} P_{TB}}{(2\pi)^{M/2} P_{NTA} P_{NTB}} \right]$$

$$P_{NTA} = \beta_{t} P_{TB} (1 - P_{TA}) + \beta_{FTB}$$

$$P_{NTB} = \beta_{t} P_{TA} (1 - P_{TB}) + \beta_{FTA}$$

Line 39, delete Equation (12) and insert

$$\delta f_{i}^{2} = \left[A_{i}^{f} - B_{a(i)}^{f} \right]^{T} \left(F_{i,a(i)} \right)^{-1} \left[A_{i}^{f} - B_{a(i)}^{f} \right] + \ln \left(\left| F_{i,a(i)} \right| \right)$$

$$J_{af} = -\overline{x}^{T} R^{-1} \overline{x} - \ln \left[(2\pi)^{M} \left| R \right| \right] - \sum_{i=1}^{m} \left\{ \delta x_{i}^{T} S_{i}^{-1} \delta x_{i} + \ln \left[\left| S_{i} \right| \right] + \delta f_{i}^{2} \quad a(i) \neq 0 \right\}$$

$$g \quad a(i) = 0$$

Mailing Address of Sender:

Baker Botts L.L.P. 2001 Ross Avenue, Suite 600 Dallas, Texas 75201-2980 Patent No. US 7,092,924 B1

Form PTO-1050

UNITED STATES PATENT AND TRADEMARK OFFICE CERTIFICATE OF CORRECTION

Patent No.: US 7,092,924 B1 Dated: August 15, 2006 Inventor(s): Mark D. Levedahl

It is certified that errors appear in the above-identified patent and that said Letters Patent is hereby corrected as shown below:

Column 8:

Line 53, after "make k assignments," delete " $0 \le k \le m$ " and insert $--0 \le k \le m$

Column 9:

Line 53, delete Equation (17) and insert

$$J_{s} - \overline{x}^{T} R^{-1} \overline{x} - \sum_{i=1}^{s} \left\{ \delta x_{i}^{T} S_{i}^{-1} \delta x_{i} + \ln \left[|S_{i}| \right] - \ln \left(d_{\min} \right) \quad a(i) \neq 0 \\ \overline{g} \qquad a(i) = 0 \right\} + \left\{ \ln \left[\left[2\pi \right]^{M} |R| \right) \quad n_{a} = 0 \\ 0 \qquad n_{a} > 0 \right\}$$

Column 12:

Line 22, after "where" delete " $k_g \ge 1$ and insert- - $k_g \ge 1$ - - .

Line 56, delete Equation (18) and insert

$$P_i = P_i + R$$

Column 14:

Line 58, Claim 2, after "associated input" delete "are" and insert - - arc - -.

Column 15:

Line 8, Claim 5, delete the equation found after "the cost function is" and insert

$$J_{s} - \overline{x}^{T} R^{-1} \overline{x} - \sum_{i=1}^{s} \left\{ \delta x_{i}^{T} S_{i}^{-1} \delta x_{i} + \ln \left[\left| S_{i} \right| \right] - \ln \left(d_{\min} \right) \quad a(i) \neq 0 \\ \overline{g} \qquad \qquad a(i) = 0 \right\} + \left\{ \ln \left[\left[2\pi \right]^{M} \left| R \right| \right) \quad n_{a} = 0 \\ 0 \qquad \qquad n_{a} > 0 \right\}$$

Column 16:

Line 20, Claim 16 delete the equation found after "the cost function is" and insert

$$J_{s} - \overline{x}^{T} R^{-1} \overline{x} - \sum_{i=1}^{s} \left\{ \frac{\partial x_{i}^{T} S_{i}^{-1} \partial x_{i} + \ln[|S_{i}|] - \ln(d_{\min})}{\overline{g}} \quad a(i) \neq 0 \right\} + \left\{ \frac{\ln([2\pi]^{M} |R|)}{0} \quad n_{a} = 0 \right\}$$

Patent No. US 7,433,931 B2

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DAL01:1083023.1

UNITED STATES PATENT AND TRADEMARK OFFICE CERTIFICATE OF CORRECTION

Patent No.: US 7,092,924 B1 Dated: August 15, 2006 Inventor(s): Mark D. Levedahl

It is certified that errors appear in the above-identified patent and that said Letters Patent is hereby corrected as shown below:

Column 16:

Line 42, Claim 17, after

delete "o the cost" and insert - - of the cost - - .

Column 17:

Line 34, Claim 27, delete the equation found after "the cost function is" and insert $J_{s} - \overline{x}^{T} R^{-1} \overline{x} - \sum_{i=1}^{s} \left\{ \delta x_{i}^{T} S_{i}^{-1} \delta x_{i} + \ln \left[\left| S_{i} \right| \right] - \ln \left(d_{\min} \right) \quad a(i) \neq 0 \\ \overline{g} \qquad a(i) = 0 \right\} + \left\{ \ln \left[\left[2\pi \right]^{M} \left| R \right| \right) \quad n_{a} = 0 \\ 0 \qquad n_{a} > 0 \right\}$

Line 48, after "M=Number of" delete "fist" and insert - - first- - .

Line 50, delete the equation after "a=Assignment vector:" and insert $a_{(i)} > 0 \rightarrow A_i$

Line 57, Claim 29, delete the equation found after "the cost function is" and insert $J_{s} - \overline{x}^{T} R^{-1} \overline{x} - \sum_{i=1}^{s} \left\{ \frac{\partial x_{i}^{T} S_{i}^{-1} \partial x_{i} + \ln[|S_{i}|] - \ln(d_{\min})}{\overline{g}} \quad a(i) \neq 0 \right\} + \left\{ \frac{\ln([2\pi]^{M} |R|)}{0} \quad n_{a} = 0 \right\}$

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